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On the Deformation of Time Harmonic Flows¹

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Abstract

It is shown that time-harmonic motions of spherical and toroidal surfaces can be deformed non-locally without losing the existence of infinitely many constants of the motion.

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As pointed out some time ago [1], surfaces moving through \mathbf{R}^3 in such a way that their (normal) velocity is always equal to the local surface-area density, \sqrt{g} (divided by some non-dynamical ‘reference-density’, ρ), have the property that the time, at which the surface Σ_t reaches a point in space, is a harmonic function. These motions are related to certain reductions of self-dual $SU(N)$ Yang-Mills theories (which play a central role in the construction of monopoles, cp. [2]), and the Lax-pair formulation of the latter can be taken over identically ([3],[4]). One can also show [5] that time-harmonic flows are, what remains when projecting certain diffeomorphism invariant Hamiltonian field theories on to the (integrable) Diff-singlet sector.

In this letter, I would like to show that time-harmonic flows may be deformed from the ‘ w_∞ ’-invariant parametrized form to ‘ W_∞ ’-invariant motions of parametrized surfaces, while keeping integrability in the form of infinitely many constants of motion. Again, the Lax-pair can be taken from the self-dual Yang-Mills theory, or rather: the Nahm equations (i.e. reduced self-dual $SU(N)$ Yang-Mills equations) are just a special case of the most natural first order (in time), quadratically non-linear, evolution equation for a set of (3) operators, X_i . The specification (of the space of operators) that will correspond to deformed time-harmonic flows of surfaces of spherical (toroidal) topology, resp. *-products on $S^2(T^2)$, is discussed in detail.

Let \mathcal{A} be a non-commutative, associative Algebra (‘of operators’) and $X_i(t)_{i=1}^N$ a set of timedependent operators satisfying the non-linear evolution equation(s)

$$\dot{X}_i = \epsilon_{ii_1 \dots i_M} X_{i_1} X_{i_2} \dots X_{i_M} \quad (1)$$

$i = 1, 2, \dots, N = M + 1$.

Using [6]/[7], one observes that (1) can be written in the form

$$\dot{L} = \left[L, M_1, \dots, M_{N-2} \right], \quad (2)$$

where L and the M ’s ($\epsilon\mathcal{A}$) are linear combinations of the X_i , depending on $[\frac{N}{2}]$ spectral parameters, and $[\cdot, \dots, \cdot]$ (a fully antisymmetric map from $\mathcal{A} \times \dots \times \mathcal{A}$ to \mathcal{A}) denotes the natural M -commutator,

$$[A_1, \dots, A_M] := \epsilon^{r_1 \dots r_M} A_{r_1} \dots A_{r_M}. \quad (3)$$

In particular, one may take

$$L = \mu(X_1 + iX_2) - \left(\frac{X_1 - iX_2}{\mu} \right) + 2X_3$$

$$M_1 = i(\mu(X_1 + iX_2) + X_3) \quad (4)$$

(just as for the reduced self-dual Yang-Mills equations, see e.g. [2]) for $N = 3$, and (just as in [6]/[7])

$$\begin{aligned} L &= \mu(X_1 + iX_2) + \tilde{\mu}(X_3 + iX_4) \\ &\quad - \frac{1}{\mu}(X_1 - iX_2) - \frac{1}{\tilde{\mu}}(X_3 - iX_4) + \sqrt{8}X_5 \\ M_1 &= \frac{i}{\sqrt{2}}\left(\mu(X_1 + iX_2) + \frac{X_5}{\sqrt{2}}\right) \\ M_2 &= \frac{i}{\sqrt{2}}\left(\tilde{\mu}(X_3 + iX_4) + \frac{X_5}{\sqrt{2}}\right) \\ M_3 &= \frac{-1}{\sqrt{2}}\left(\frac{(X_1 - iX_2)}{\mu} - \frac{(X_3 - iX_4)}{\tilde{\mu}}\right) \end{aligned} \quad (5)$$

for $N = 5$.

If there exists a trace on \mathcal{A} , satisfying

$$TrAB = TrBA, \quad (6)$$

$$Q_n := TrL^n, \quad n \in \mathbf{N} \quad (7)$$

will be automatically time-independent only for $N = 3$; for odd $N > 3$, at least Q_1 and Q_2 are conserved, while for even N not even the basic M -commutator is traceless.

In the following, I will restrict myself to the case $N = 3$, i.e.

$$\dot{X}_i = \frac{1}{2}\epsilon_{ijk}[X_j, X_k] \quad (8)$$

which, if the X_i were finite-dimensional matrices, are just ‘Nahm’s equations’. They still trivially ‘are’, for infinite matrices with finitely many non-zero coefficients, but ‘all’ other infinite dimensional choices for \mathcal{A} (or rather: an infinite-dimensional Lie-algebra, \mathcal{L}) are of quite different nature, and it seems that only the time-harmonic [1]/[5], w_∞ -invariant case (area-preserving limit of $SU(N)$ [8],[3],[4]), where \mathcal{L} is the Lie algebra of (non-constant) symplectic diffeomorphisms of S^2 or $T^2 \dots$, (8) becoming the following set of

first order partial differential equations for time-dependent functions on a two-dimensional manifold Σ ,

$$\dot{x}_i = \frac{1}{2} \epsilon_{ijk} \frac{\epsilon^{rs}}{\rho(\phi)} \frac{\partial x^j}{\partial \phi^r} \frac{\partial x^k}{\partial \phi^s}, \quad (9)$$

has previously been considered in the literature ([3] - [7]). Here, I would like to consider *-product deformations of (9), which amounts to (for S^2 , [9]) choosing \mathcal{A} to be the enveloping algebra of $SO(3)$, divided by the ‘Casimir-ideal’, or (for T^2) specific subclasses of infinite-dimensional matrices with only finitely many non-zero off-diagonals (cp. [10]). Both series of infinite dimensional ‘ W_∞ ’-algebras admit an invariant trace, making (7) time-independent for all n .

Let me first discuss the ‘spherical type’ W^∞ -algebras (cp. [9], [11]).

Let \mathcal{G} be a semi-simple Lie-algebra, $\{T_a\}_{a=1}^{d=\dim \mathcal{G}}$ a basis of \mathcal{G} ,

$$[T_a, T_b] = f_{ab}^c T_c \quad abc = 1 \dots d \quad (10)$$

and $U(\mathcal{G})$ be the associative algebra (over \mathbf{C}) of polynomials

$$T = c_T \cdot \mathbf{1} + \sum c^{a_1 \dots a_l} T_{a_1} \dots T_{a_l}, \quad (11)$$

modulo (10) (i.e. the universal enveloping algebra). The center of U is generated by $r = \text{rank} \mathcal{G}$ ‘Casimirs’ C_1, \dots, C_r , and U may be divided by the sum of the r two-sided ideals

$$I_j = (C_j - \lambda_j \mathbf{1})U, \quad \lambda_j \in \mathbf{C}; \quad (12)$$

resulting in $U_{\lambda=(\lambda_1, \dots, \lambda_r)}(\mathcal{G})$, the algebra of polynomials

$$T^{(\lambda)} = c_T \mathbf{1} + \sum c_T^{a_1 \dots a_l} T_{a_1}^{(\lambda)} \dots T_{a_l}^{(\lambda)}, \quad (13)$$

where the $T_a^{(\lambda)}$ are irreducible representations of (10), having the property that certain polynomials, like

$$C_1^{(\lambda)} := T_a T_b g^{ab} = \lambda_1 \cdot \mathbf{1} \quad (14)$$

(g^{ab} being the inverse of $g_{ab} := \frac{1}{2} f_{ac}^d f_{bd}^c$, the metric tensor on \mathcal{G}) are proportional to $\mathbf{1}$, and the coefficients $c^{a_1 \dots a_l}$ apart from (for definiteness)

being totally antisymmetric, will consequently be taken to satisfy additional requirements like $g_{ab}c^{aba_3\dots a_l} \equiv 0, \dots$ (in accordance with the r Casimir relations). It is known (see e.g. [12]) that $U_\lambda(\mathcal{G})$ decomposes, under the action of \mathcal{G} , into a direct sum of finite dimensional irreducible \mathcal{G} -modules,

$$U_\lambda = \oplus \sum_{(t)_j} U_\lambda^{(t)_j}, \quad (15)$$

$j = 1 \dots m(t)$, where each (tensor) representation (t) occurs finitely many $(m_{(t)})$ times; the 1-dimensional representation occurs only once and, as $[U_\lambda, U_\lambda] = [\mathcal{G}_\lambda, U_\lambda]$ (see [13]), it is easy to see that U_λ is also the direct sum

$$U_\lambda = \mathbf{C} \cdot \mathbf{1} \oplus [U_\lambda, U_\lambda], \quad (16)$$

implying that

$$TrT := c_T \quad (17)$$

defines an invariant trace on U_λ , $Tr[A, B] = 0$ – which is all one needs to conclude that (8), with $\mathcal{A} = U_\lambda(\mathcal{G})$, will have infinitely many conserved quantities, (7). I am referring to the series of algebras $U_\lambda(\mathcal{G})$ as the ‘spherical series’ as in the simplest case, $\mathcal{G} = SO(3)$, the (to be extended) map $\phi_{\hbar := \frac{1}{\lambda}}$,

$$\begin{aligned} Y_{lm}(\theta, \phi) &= \left(\sum c_{a_1 \dots a_l}^{(lm)} x_{a_1} \cdot \dots \cdot x_{a_l} \right)_{\vec{x}=(\sin \theta \cos \phi, \sin \theta \sin \phi, \cos \theta)} \\ \longrightarrow \phi_{\hbar}(Y_{lm}) &= \bar{T}_{lm}^{(\lambda)} := c_{(l)}^{(\lambda)} \sum c_{a_1 \dots a_l}^{(lm)} \bar{T}_{a_1 \dots}^{(\lambda)} \bar{T}_{a_l}^{(\lambda)}, \end{aligned} \quad (18)$$

where $[\bar{T}_a^{(\lambda)}, \bar{T}_b^{(\lambda)}] = \frac{\epsilon_{abc}}{\lambda} \bar{T}_c^{(\lambda)}$, $\sum_{a=1}^3 \bar{T}_a^{(\lambda)} \bar{T}_a^{(\lambda)} = \mathbf{1}$, provides a one to one correspondence between $U_\lambda(SO(3))$ and the (commutative, resp. Poisson-) algebra of complex-valued functions on S^2 (cp. [8], [14]). Moreover, the overall normalisation may be chosen such that when $\hbar = \frac{1}{\lambda}$ is appropriately taken to 0,

$$\begin{aligned} \frac{1}{i\hbar} [\phi_{\hbar}(Y_{lm}), \phi_{\hbar}(Y_{l'm'})] &\rightarrow \{Y_{lm}, Y_{l'm'}\} \\ &:= \frac{1}{\sin \theta} \left(\frac{\partial Y_{lm}}{\partial \theta} \frac{\partial Y_{l'm'}}{\partial \phi} - (lm \longleftrightarrow l'm') \right) \end{aligned} \quad (19)$$

– which together with suitable properties under complex (hermitean) conjugation, ... (see [15] for the definition of a star-product) allows to call the associative multiplication in $U_\lambda(SO(3))$ a *-product on S^2 :

$$Y_{lm} * Y_{l'm'} := \phi_{\hbar}^{-1}(\phi_{\hbar}(Y_{lm})\phi_{\hbar}(Y_{l'm'})). \quad (20)$$

For the ‘Torus-case’, where a *-product may easily be written directly in terms of functions on T^2 ,

$$f * g := f \cdot g + \sum_{n=1}^{\infty} \frac{(\lambda/2)^n}{n!} \epsilon^{r_1 s_1} \dots \epsilon^{r_n s_n} \frac{\partial^n f}{\partial \phi^{r_1} \dots \partial \phi^{r_n}} \frac{\partial^n g}{\partial \phi^{s_1} \dots \partial \phi^{s_n}}, \quad (21)$$

the equation

$$\lambda \dot{x}_i = \epsilon_{ijk} x_j * x_k, \quad (22)$$

viewed as an evolution-equation for a hypersurface in \mathbf{R}^3 , may then ‘at any stage’ (s.b.) be compared with the time-harmonic flow (9) (which is equivalent to (22), $\lambda = 0$). In view of (9) being equivalent to (cp. [1])

$$\vec{\nabla}^2 t(x^1, x^2, x^3) = 0, \quad (23)$$

it is tempting to interchange dependent and independent variables also in (22): making this ‘hodograph’ transformation,

$$\phi^o = t, \phi^1, \phi^2 \rightarrow x^i := x^i(t, \phi^1, \phi^2), \quad (24)$$

one first notes the purely ‘kinematical’ consequences,

$$\begin{aligned} \dot{\vec{x}} &\hat{=} J(\vec{\nabla}\phi^1 \times \vec{\nabla}\phi^2) \\ J &= |(\frac{\partial x^i}{\partial \phi^\alpha})| = \dot{\vec{x}}(\partial_1 \vec{x} \times \partial_2 \vec{x}) = (\vec{\nabla}t \cdot (\vec{\nabla}\phi^1 \times \vec{\nabla}\phi^2))^{-1} \\ \partial_t &\hat{=} \dot{\vec{x}} \cdot \vec{\nabla} = J(\vec{\nabla}\phi^1 \times \vec{\nabla}\phi^2) \cdot \vec{\nabla} =: D_o \\ \frac{\partial}{\partial \phi^r} &\hat{=} J(\vec{\nabla}t \times \vec{\nabla}\phi^r) \cdot \vec{\nabla} =: D^r \\ D^r \phi^s &= \epsilon^{rs}, \quad [D^\alpha, D^\beta] = 0, \end{aligned} \quad (25)$$

$\alpha, \beta = 0, 1, 2$

while (22) becomes

$$\begin{aligned} (\vec{\nabla}\phi^1 \times \vec{\nabla}\phi^2)_i &= \frac{\epsilon_{ijk}}{\lambda J} e^{\frac{\lambda}{2} \epsilon_{rs} D^r \otimes D^s} x_j \otimes x_k \Big|_{\text{Diag.}} \\ &= (\vec{\nabla}t)_i \\ &+ \frac{1}{2J} \epsilon_{ijk} \sum_{l=1}^{\infty} \frac{(\lambda^2/4)^l}{(2l+1)!} (\epsilon_{rs} D^r \otimes D^s)^{2l+1} x_j \otimes x_k \Big|_{\text{Diag.}} \\ &=: (\vec{\nabla}t)_i + \sum_{l=1}^{\infty} (\lambda^2)^l (\vec{F}_l(\vec{\nabla}t, \vec{\nabla}\phi^1, \vec{\nabla}\phi^2))_i. \end{aligned} \quad (26)$$

Note that just as $\sum_i [x_i, \dot{x}_i]_* = 0$ is a consequence of (22), solutions of (26) will satisfy

$$\sum_i e^{\frac{\lambda}{2} \epsilon_{rs} D^r \otimes D^s} \left(x_i \otimes J(\vec{\nabla} \phi^1 \times \vec{\nabla} \phi^2)_i - J(\vec{\nabla} \phi^1 \times \vec{\nabla} \phi^2)_i \otimes x_i \right) \Big|_{\text{Diag.}} = 0 \quad (27)$$

At least recursively, (26) is still solvable, as expanding the 3 unknown functions t, ϕ^1, ϕ^2 into powerseries in λ^2 ,

$$\begin{aligned} t(\vec{x}) &= T(\vec{x}) + \sum_{n=1}^{\infty} \lambda^{2n} t_n(\vec{x}) \\ \phi^r(\vec{x}) &= \phi^r(\vec{x}) + \sum_{n=1}^{\infty} \lambda^{2n} \phi_n^r(\vec{x}), \end{aligned} \quad (28)$$

the zero'th order (non-linear) ones are solvable, while all the higher ones are (recursively) linear; in particular, all $t_n(\vec{x})$ are given as solutions of Poisson's equation,

$$\vec{\nabla}^2 t_n(\vec{x}) = \vec{\nabla} G_n, \quad (29)$$

with G_n only depending on the $t_{m < n}$, $\phi_{m < n}^1$ and $\phi_{m < n}^2$. Of course, it would be desirable to derive (from (26)) an equation only involving t .

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